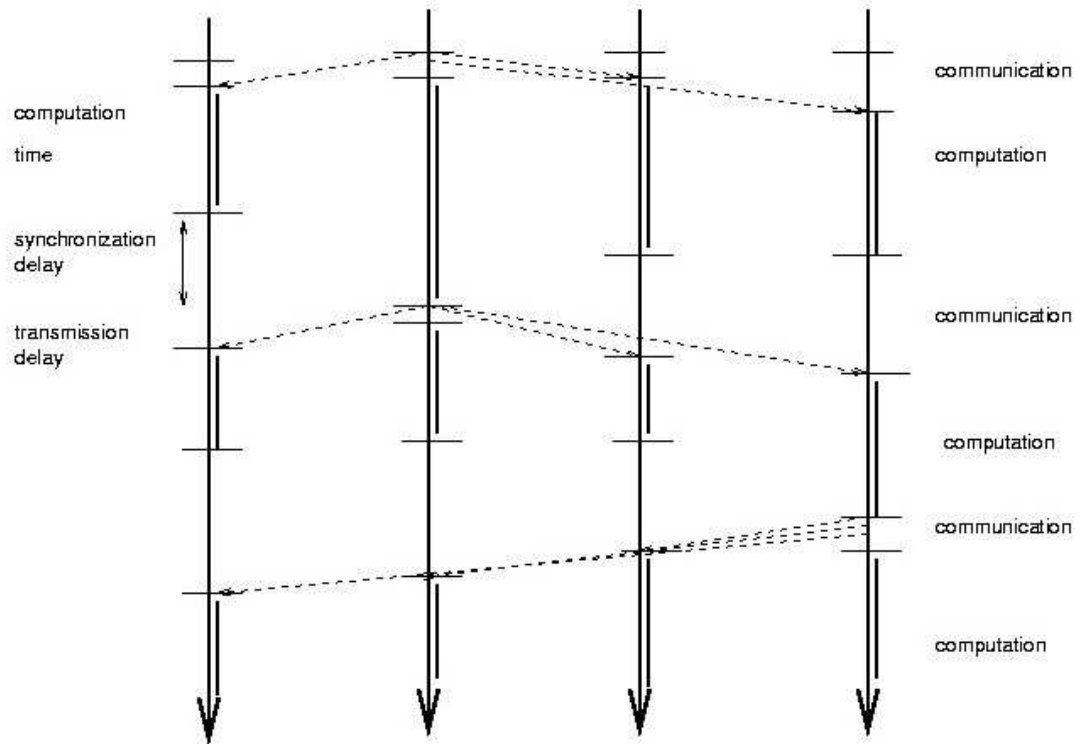


A model for Entropy of Parallel Execution

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Irregular execution and communications



Parallel execution:

Definition 2.1. A *parallel state* is a pair $S_{G,J} = (x_J, D_J^G)$, indexed by a step counter J which is a multi-index $J = J_G = \{(j_p) \mid p \in G\}$.

Definition 2.2. A *parallel transition* is a relation $S_{G,J} \rightarrow S_{H,K}$ between a pair of parallel states such that

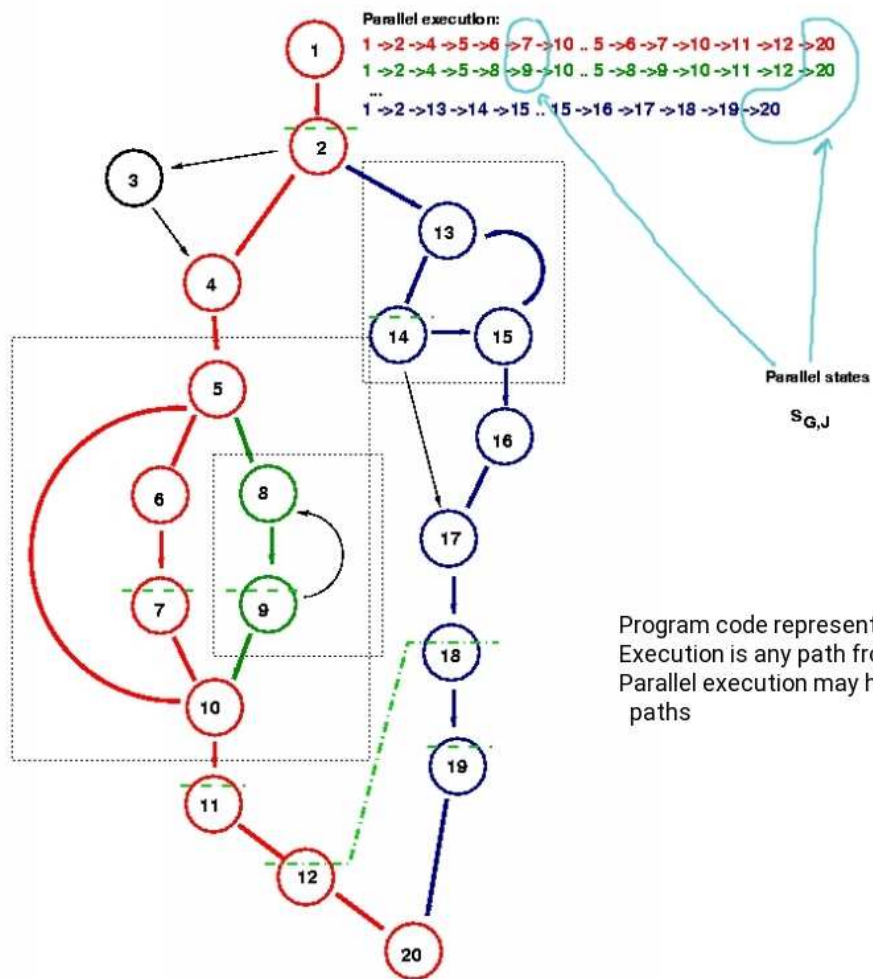
- $G \cap H \neq \emptyset$
- for each $p \in G \cap H$, we have $k_p - j_p \leq 1$, and
- for at least one $p \in G \cap H$ we have $k_p - j_p > 0$.

Definition 2.3. Let $T = (S_{G^1, J^1} \rightarrow S_{G^2, J^2} \rightarrow \dots)$ be any sequence of parallel transitions relating parallel states. (Note that $G_i \cap G_{i+1}$ needs to contain at least one element, but there is no other restriction on the G_i .) The *p-trace* of T is the list of serial state indices $\tau_p = (j_p^{i_1}, j_p^{i_2}, \dots, j_p^{i_k})$ in the order in which those states appear in T . Note that, since p is not necessarily found in every G_i , the superscripts i_ℓ are not necessarily consecutive. We will say that a *p-trace* τ_p is *time-like* if $j_p^{i_{\ell+1}} \geq j_p^{i_\ell}$ for all ℓ .

Definition 2.4. An *SPMD parallel execution* E is a directed graph of transitions starting at $E_{G_{tot}} = S_{G_{tot}, 0}$ all of whose *p-traces* (def: 2.3) are time-like.

Motivation:

1. Experimentally explore non-determinism in parallel state and execution
2. Verify that synchronization is detectable in execution, find other features that consistently appear in visualization
3. Characterize hardware-independent costs of synchronization (and other constructs) by analysis of entropy



Parallel execution:

1 → 2 → 4 → 5 → 6 → 7 → 10 .. 5 → 6 → 7 → 10 → 11 → 12 → 20

1 → 2 → 4 → 5 → 8 → 9 → 10 .. 5 → 8 → 9 → 10 → 11 → 12 → 20

...

1 → 2 → 13 → 14 → 15 .. 15 → 16 → 17 → 18 → 19 → 20

Parallel states

$S_{G,J}$

Program code represented as basic blocks
 Execution is any path from start to end block
 Parallel execution may have different concurrent paths

non-deterministic transition

0 → 1 → 2 2

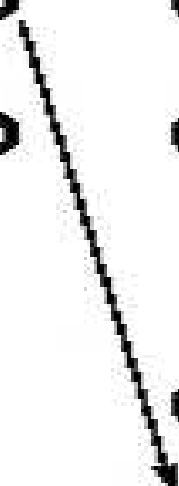
0 0 → 1 → 2

0 0 1 1

0 → 1 1

1 1 → 2

0 0 0



Parallel state is list of concurrent blocks
-> multiple possible successor states

SPMD model used for simpler representation, but not restricted to this model.

Represent code as Control Flow Graph CFG

Process q state is basic block x and memory contents M at step j

$$\sigma_{q,j} = (x_j, M_j)$$

Execution is a series of states representing a walk through CFG

$$S_{\Gamma,J} = \{\sigma_{i,j}\}$$

A parallel state is the set of sequential states occurring concurrently

Gamma is the ordered set of processes and J the ordered set of step numbers - a parallel transition occurs when 1 or more processes advance - even if processes are deterministic, parallel transition is not

Representing each state as a P-tuple of concurrent block numbers gives us a P dimensional hypercube with side=number of blocks.

Some features in the phase space repeat (synchronization code in specific blocks). Most states are not deterministic and won't repeat.

Given a set of points corresponding to one or a set of executions, Gibbs-Shannon entropy is:

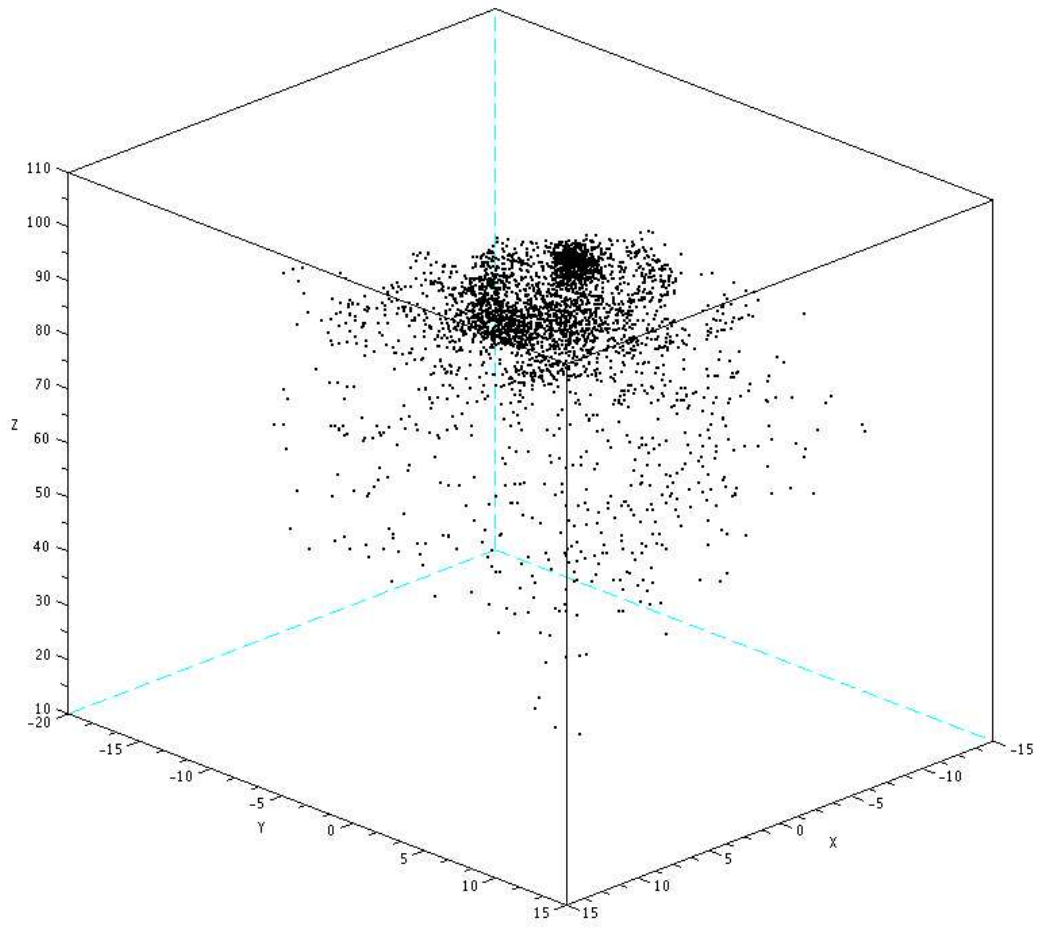
$$- \sum p_i \log_2(p_i)$$

We use standard combinatoric properties to calculate the probabilities:

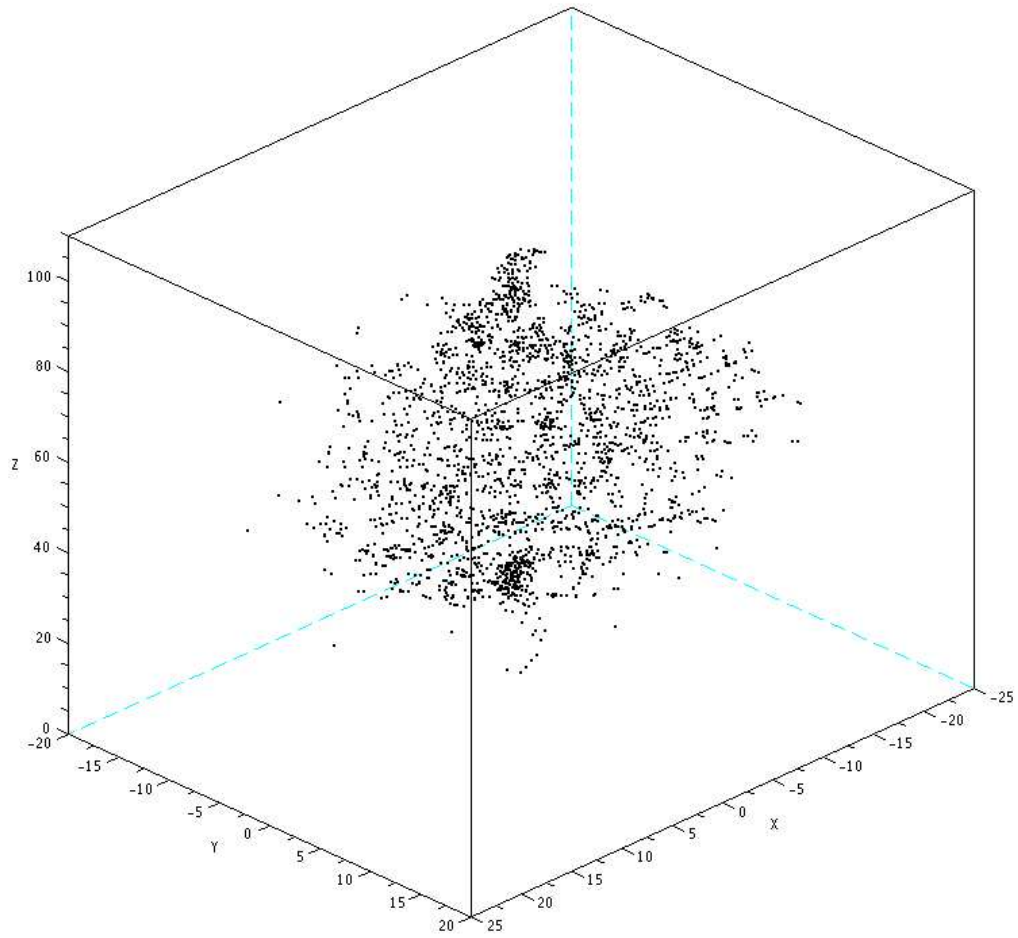
$$p_i = \frac{P!}{N^P \prod (b_k)!}$$

Where the b_k are subsets in the state with the same block number and we normalize to the total phase space hypervolume

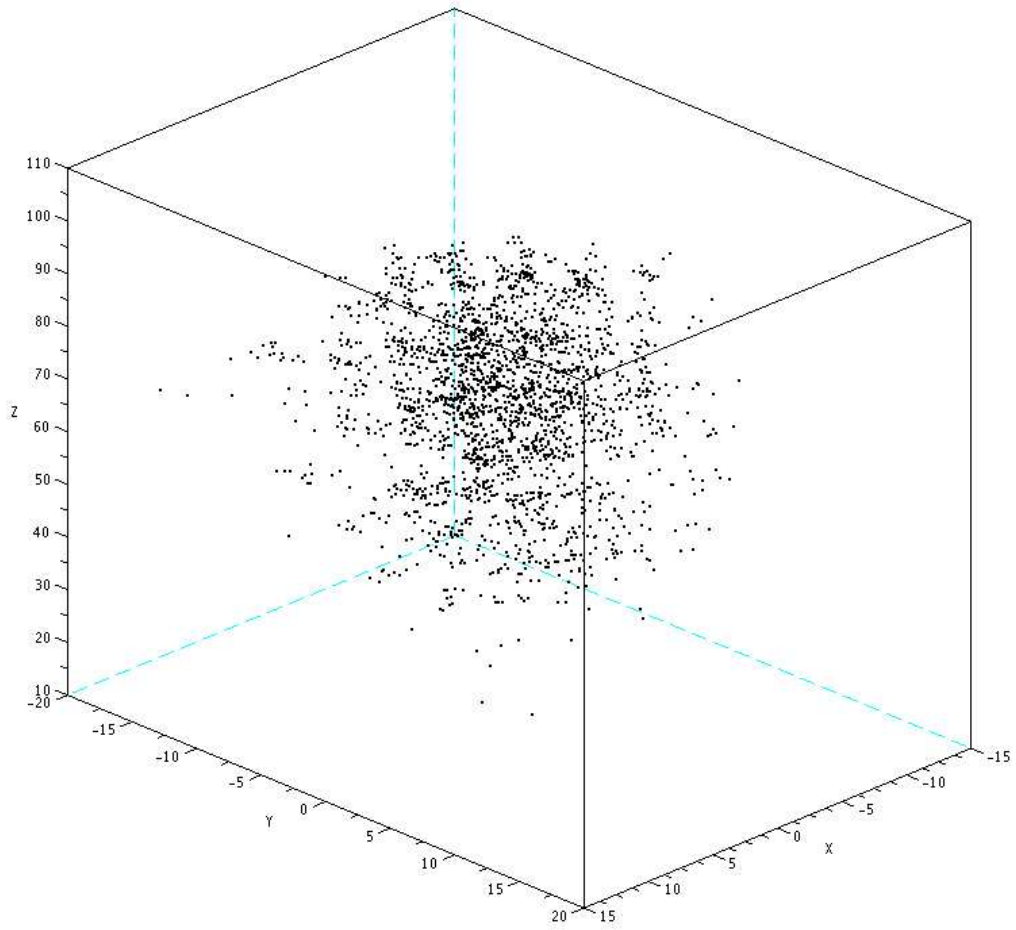
MPI Synchronous, 17 processes



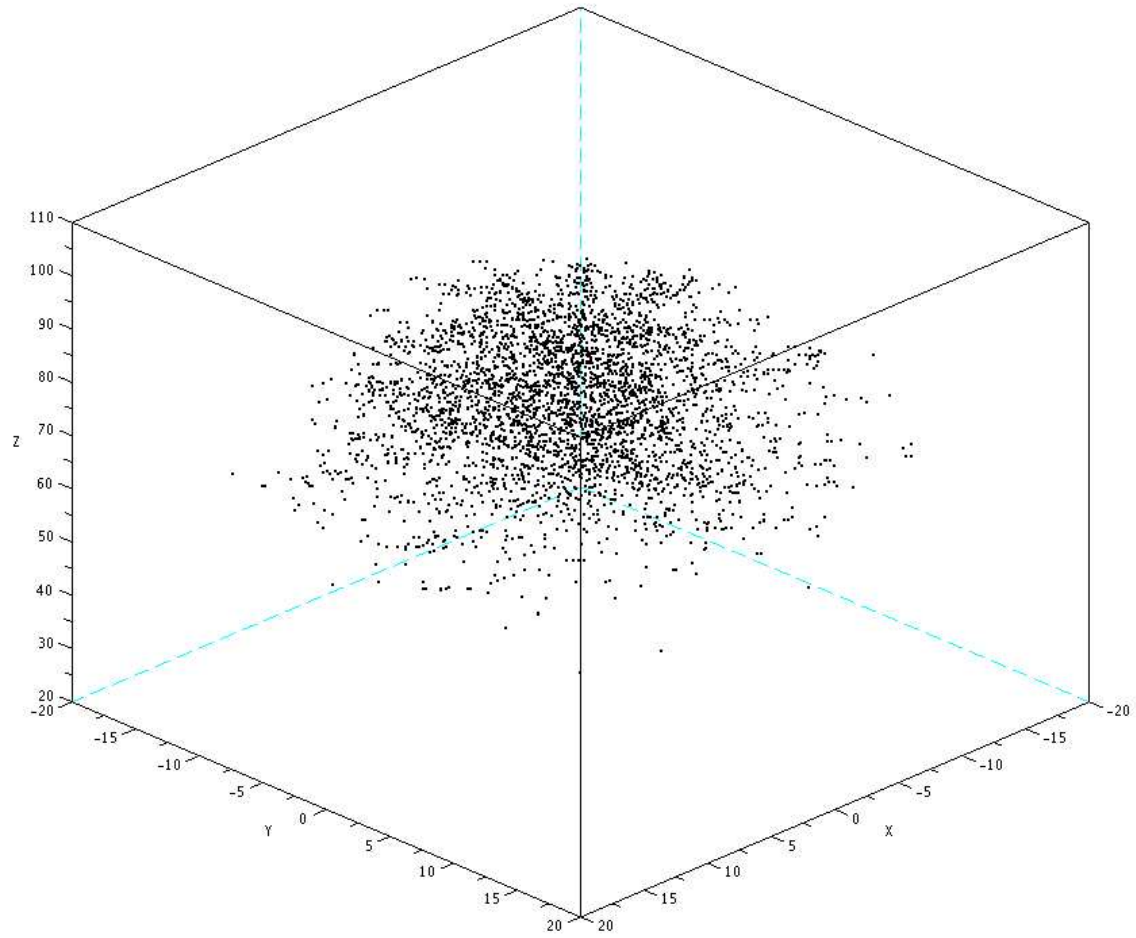
SOS asynchronous, 17 processes



No communication , 17 processes



No communications, guided, 17 processes

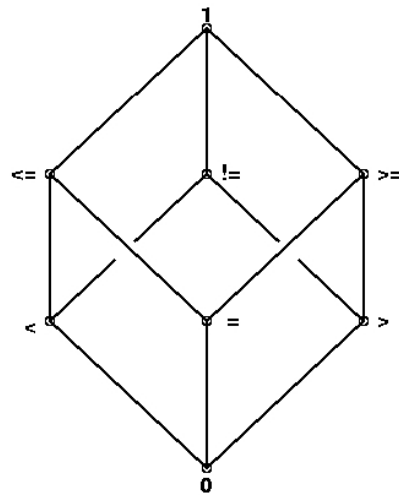


Algebra

$S = \{1, \geq, \leq, =, >, <, 0\}$ is complete

Lattice closed under intersection, union and complement, with 0 and 1 is a Boolean Algebra

S with set operations is \mathbf{B}^3



phase space reduction:

">" synchronization removes 1 quadrant - $R=.75$ of phase space per dimension
"=" synchronization removes 2 quadrants - $R=.5$ of phase space per dimension

given unsynchronized entropy S , then entropy with synchronization S' is given by
 $S' = \log(\exp(S) * R^N)$ (given interval between synch longer than relaxation time)

Time prediction - $dt/t = \log(N) * dS/S$ (the $\log N$ factor assumes collective communication tree)

AMOEBa - time:

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TARDIS: comparison of amoebampi and amoebaM (no synch)

17 amoebasos.mat entropy = 12.06215727 mean state size 5.340149838 time 2550742
17 amoebampi.mat entropy = 11.40358976 mean state size 5.660535992 time 1842581
17 amoebaN.mat entropy = 12.53261805 mean state size 5.178458642 time 991982
17 amoebaM.mat entropy = 14.42974945 mean state size 4.930923558 time 603365

dt/T = 0.763455104436278 (expected)

dt/T = 0.46486557378577 (actual)

RAVEN: comparison of amoebampi and amoebaM (no synch)

17 amoebasos.mat entropy = 11.79212385 mean state size 5.21425634 time 13013195
17 amoebampi.mat entropy = 10.85077704 mean state size 5.616563899 time 6372684
17 amoebaN.mat entropy = 12.78105428 mean state size 4.997991238 time 3577237
17 amoebaM.mat entropy = 16.32720129 mean state size 4.387070064 time 981748

dt/T = 0.924557497217248 (expected)

dt/T = 0.78695924005089

AMOEBa - entropy prediction

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RAVEN: 11.4094047683197 - expected 11.79

TARDIS: 9.40940476831973 - expected 12.06215727

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